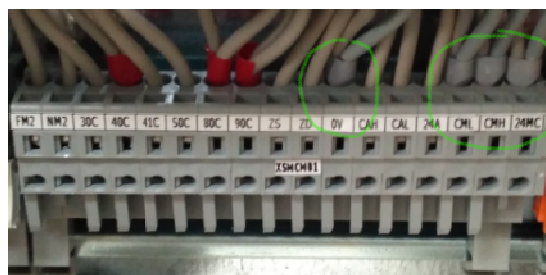
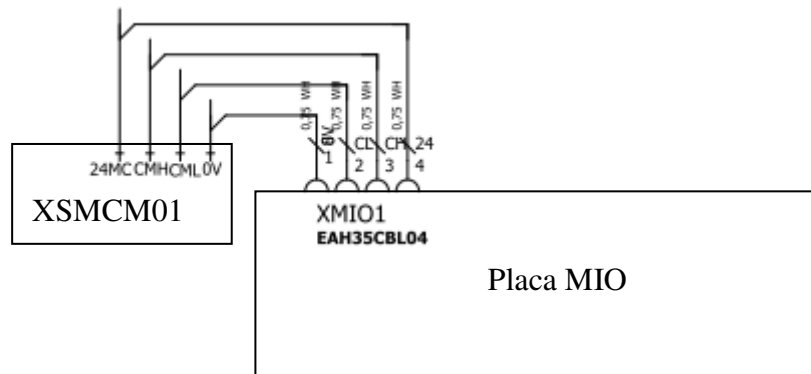


-Ubicación placa MIO

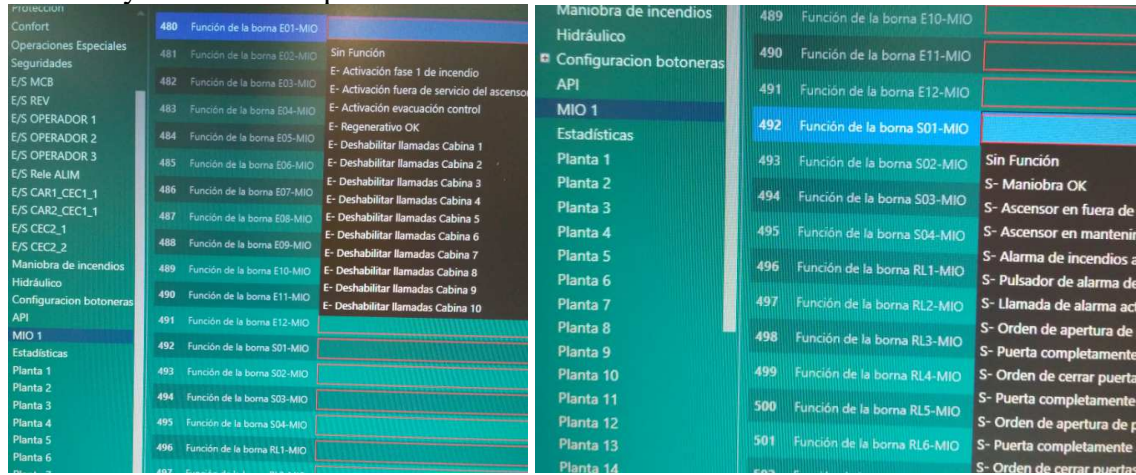
Se ubicará en el mismo hueco disponible para la placa LINK, de coincidir con ésta irá ubicada encima de la placa LINK mediante unos elevadores de 40mm, que sustituyen a las tuercas que sujetaban la placa LINK, de manera que apilando ambas no molesta para la protección integral.



-Cableado placa MIO, para comunicar la placa MIO con la maniobra es necesario cablear en paralelo la alimentación y el bus, esta operación se realiza mediante punteras dobles en el conector XSMCM01 (situado en carriles inferiores) desde el conector XMIO1 de la placa MIO.

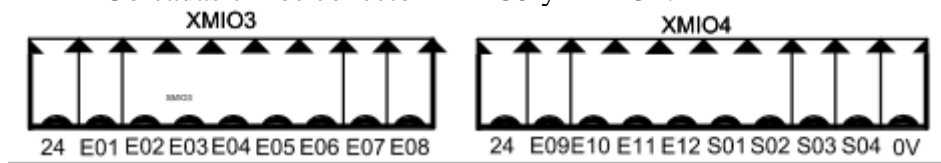


-Parametrización, desde ecoGO tools se puede encontrar en la carpeta MIO, para las entradas y las salidas disponibles.



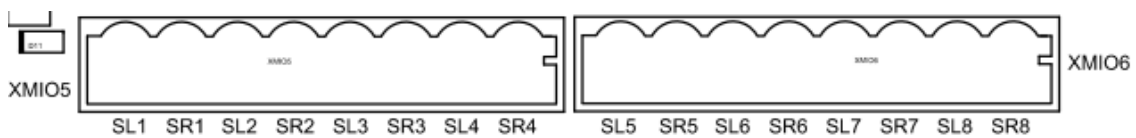
-Entradas y salidas digitales (24Vdc).

Ubicadas en los conector XMIO3 y XMIO4.



-Salidas contacto libre de tensión.

Ubicadas en los conectores laterales de la placa, XMIO5 y XMIO6.

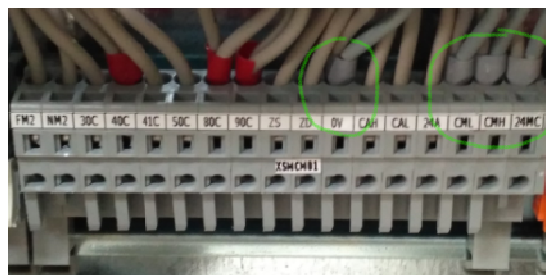
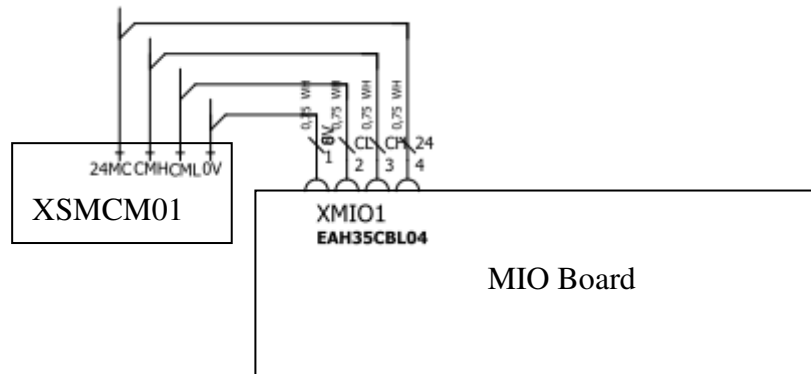


-MIO board location

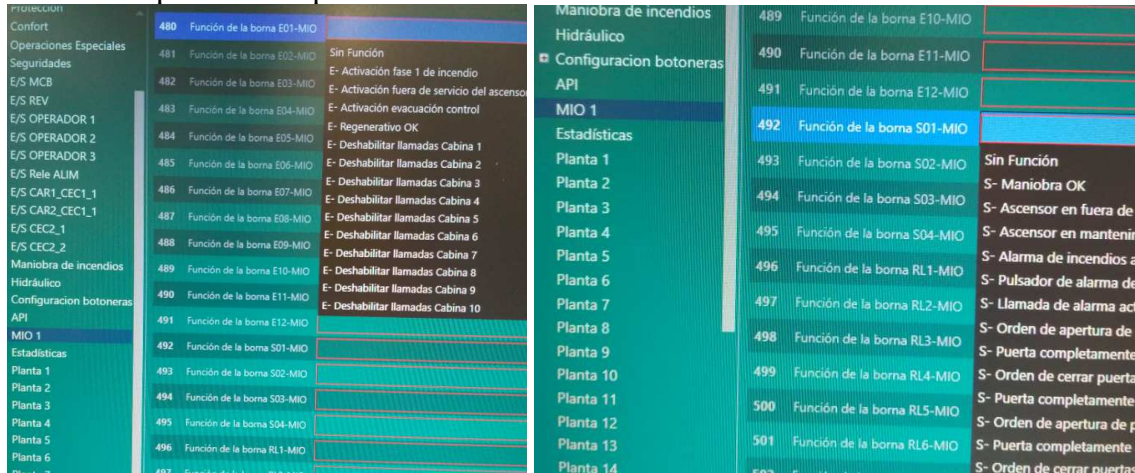
It will be located in the same place available for the LINK board, if it coincides with it, it will be located on top of the LINK board by means of 40mm elevators, which replace the nuts that held the LINK board, so that stacking both doesn't disturb the plastic protection.



-MIO board wiring, to communicate the MIO board with the maneuver it is necessary to wire the power supply and the bus in parallel, this operation is carried out by means of double terminal in the XSMCM01 connector (located in lower rails) from the XMIO1 connector of the MIO board.



-Parameterization, with ecoGO tools, it can be found in the MIO folder, see the available inputs and outputs.



-Digital Inputs and Outputs (24Vdc).

Located it on XMIO3 and XMIO4 connectors.



-Free Voltage Contact Output.

Located it on XMIO5 and XMIO6.

